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A New 3D
Parallel
Thinning
Scheme Based
on Critical
Kernels

Gilles
Bertrand and
Michel
Couprie

A New 3D Parallel Thinning Scheme Based on Critical Kernels

Gilles Bertrand and Michel Couprie

Laboratoire A2SI, Groupe ESIEE
IGM, Unité Mixte de Recherche CNRS-UMLV-ESIEE UMR 8049

October 23, 2006

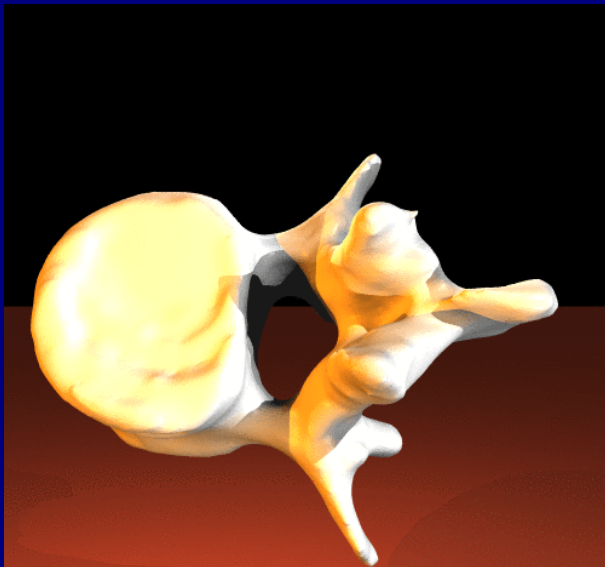


Parallel 3D thinning

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Milestones

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- 1966: D. Rutovitz – first parallel thinning algorithm



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- Since then, many parallel thinning algorithms have been proposed, described by sets of masks



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- 1988: C. Ronse – minimal non-simple sets
- allows checking the topological soundness of parallel thinning algorithms



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- 1995: G. Bertrand – P-simple points
- allows checking the topological soundness of parallel thinning algorithms
- \dagger : constitutes a general thinning scheme which may be instantiated into many different algorithms



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2005: Critical kernels



Plan of the presentation

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- Cubical complexes and simple faces
- Critical kernels
- New 3D Parallel Thinning Scheme
- Local characterizations and thinning algorithms
- Conclusion and perspectives



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Part I

Cubical complexes



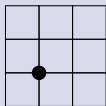
Face

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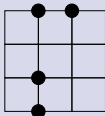
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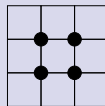
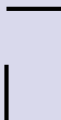
- A subset of \mathbb{Z}^n composed of one point is called a **0-face**.
- A subset of \mathbb{Z}^n forming a unit bipoint is called a **1-face**.
- A subset of \mathbb{Z}^n forming a unit square is called a **2-face**.
- A subset of \mathbb{Z}^n forming a unit cube is called a **3-face**.



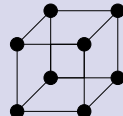
0-face



1-faces



2-face



3-face





Closure

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Let f be a face.

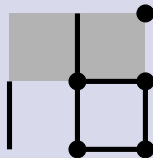
- The **closure** of f , denoted by \hat{f} , is the set composed by all the faces which are included in f .
- The set \hat{f} is called a **cell**.
- If X is a finite set of faces, we write $X^- = \cup\{\hat{f} \mid f \in X\}$, X^- is the **closure of X** .



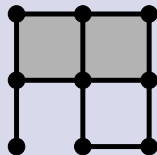
f



\hat{f}



X



X^-



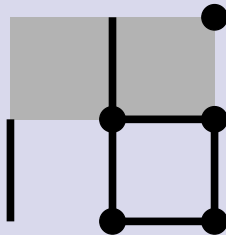
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Cubical complex

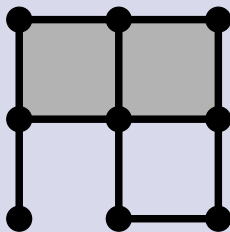
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A finite set X of faces is a **complex** if $X = X^-$.



not complex



complex



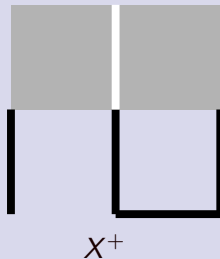
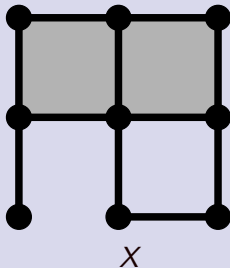
Principal face

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- A face $f \in X$ is **principal** if there is no $g \in X$ such that f is strictly included in g .
- We denote by X^+ the set composed of all principal faces of X .





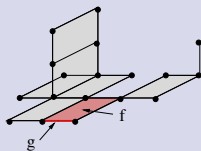
Elementary collapse

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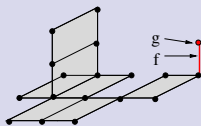
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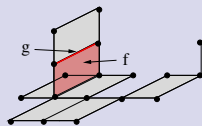
- Let f and g be two distinct faces such that f is the only face of X which contains g .
- The complex $X \setminus \{f, g\}$ is an **elementary collapse** of X .



(a)



(b)



(c)

In (a) and (b), $X \setminus \{f, g\}$ is an elementary collapse of X .
In (c), $X \setminus \{f, g\}$ is **not** an elementary collapse of X .

Important: collapse preserves topology



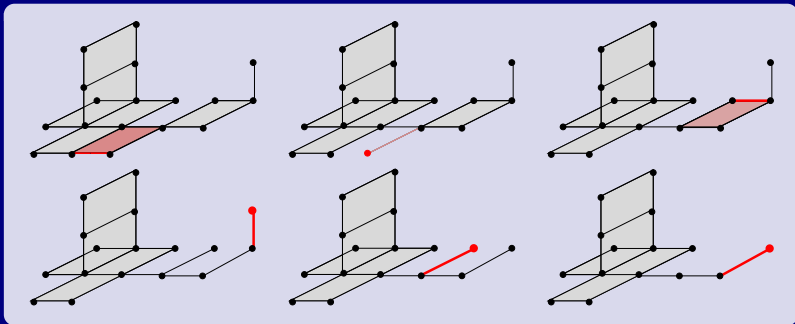
Collapse sequence, retraction

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- Let X, Y be two complexes. We say that X collapses onto Y if there exists a collapse sequence from X to Y .
- If X collapses onto Y , we also say that Y is a retraction of X .





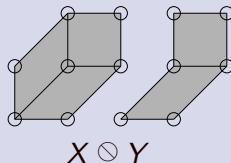
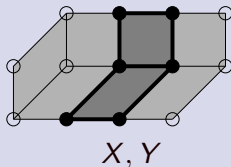
Detachment

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Let Y be a subset of X . We set $X \ominus Y = [X^+ \setminus Y^+]^-$. The set $X \ominus Y$ is a complex which is the **detachment of Y from X** .





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New definition for simplicity

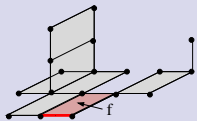
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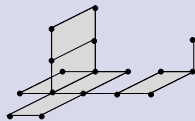
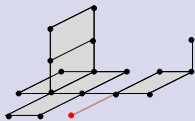
Intuitively, a face f of a complex X is simple if its removal from X “does not change the topology of X ”.

Definition

Let f be a principal face, we say that f is **simple** if X collapses onto $X \ominus f$.



X



$X \ominus f$

The face f is simple.



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Part II

Critical kernels



Key notions

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This framework for the study of parallel thinning in any dimension is based on three new notions:

- Essential face
- Core of a face
- Regular/critical face



Essential face

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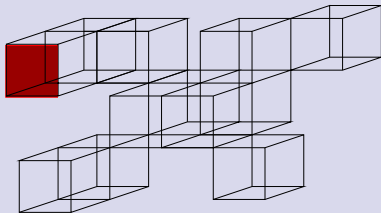
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Definition

- We say that f is an **essential face** if f is precisely the intersection of all principal faces of X which contain f .
- We denote by $Ess(X)$ the set composed of all essential faces of X .

Note: Any principal face is essential.



The 2-face is **not** essential



Essential face

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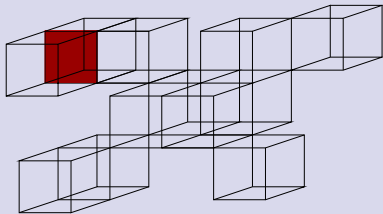
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The 2-face is essential



Essential face

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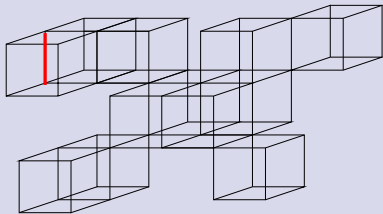
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The 1-face is **not** essential



Essential face

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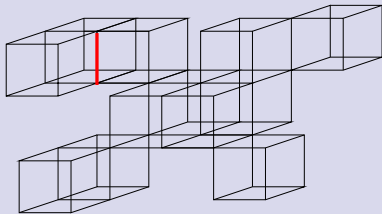
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The 1-face is essential



Essential face

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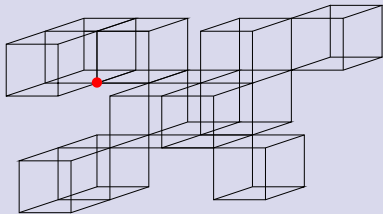
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The 0-face is **not** essential



Essential face

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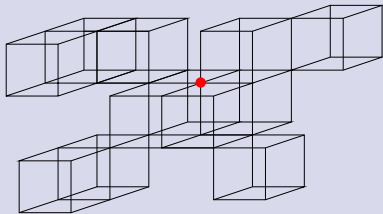
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The 0-face is essential



Core

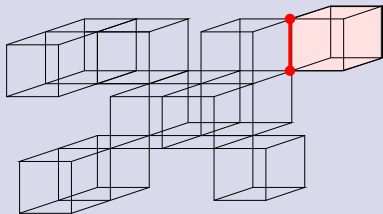
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Definition

- The **core** of f is the complex, denoted by $Core(f, X)$, composed by all the essential faces which are strictly included in f , and all the faces included in these faces.



A 3-face and its core



Core

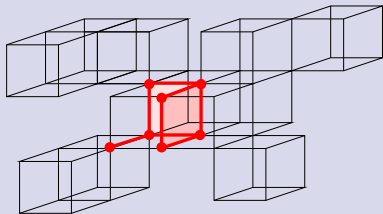
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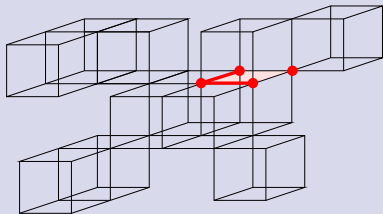
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A 2-face and its core



Regular/critical face

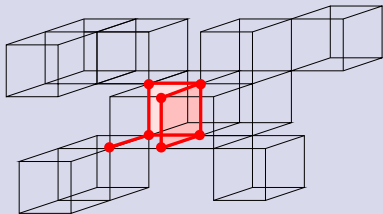
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Definition

- We say that f is **regular** if $f \in \text{Ess}(X)$ and if \hat{f} collapses onto $\text{Core}(f, X)$.
- We say that f is **critical** if $f \in \text{Ess}(X)$ and if f is not regular.



The 3-face is regular



Regular/critical face

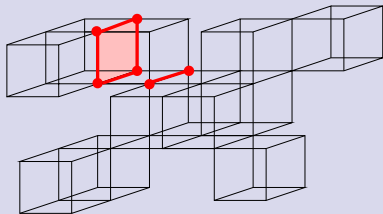
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The 3-face is critical



Regular/critical face

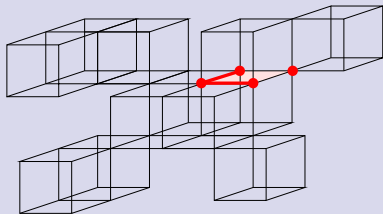
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The 2-face is critical



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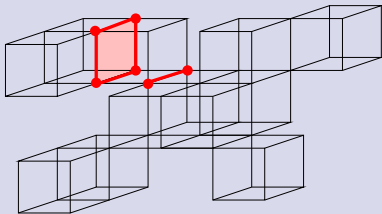
Local characterization of simple faces

Property

A principal face of a complex X is simple if and only if it is regular.

Note

We retrieve a local characterization established by T.Y. Kong, based on the notion of attachment.



The 3-face is **not** simple



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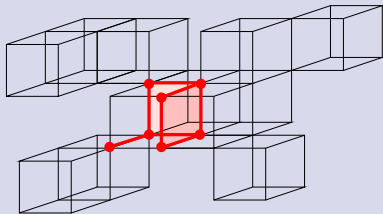
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The 3-face is simple



Critical kernel

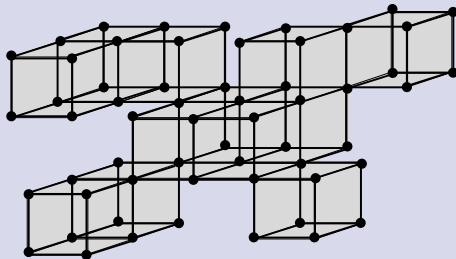
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Definition

- We set $Critic(X) = \cup \{ \hat{f} \mid f \text{ is critical} \}$, $Critic(X)$ is the critical kernel of X .



A complex X



Critical kernel

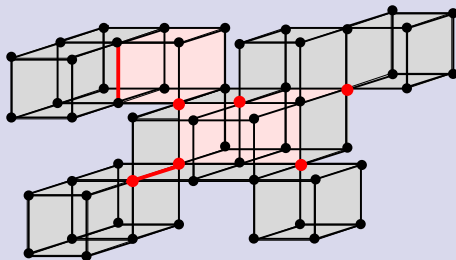
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The critical faces of X



Critical kernel

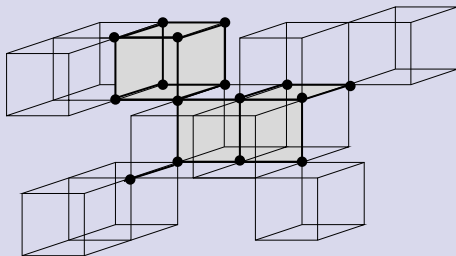
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The critical kernel of X



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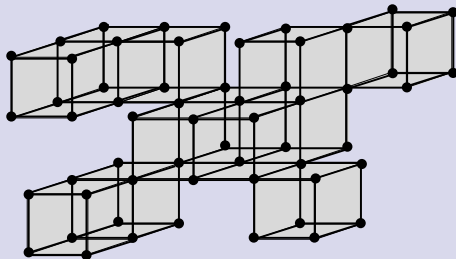
Main theorem (1)

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Theorem

In any dimension, the critical kernel of X is a retraction of X .



A complex X



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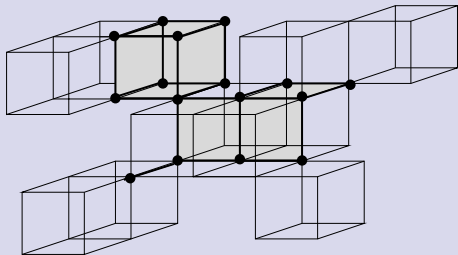
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Theorem

In any dimension, the critical kernel of X is a retraction of X .



$X_1 = \text{Critic}(X)$, a retraction of X



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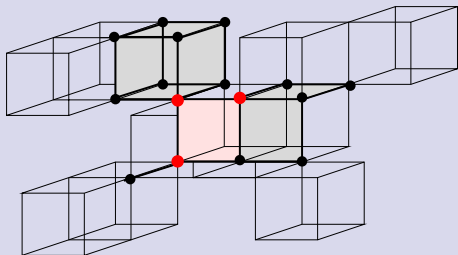
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The critical faces of X_1



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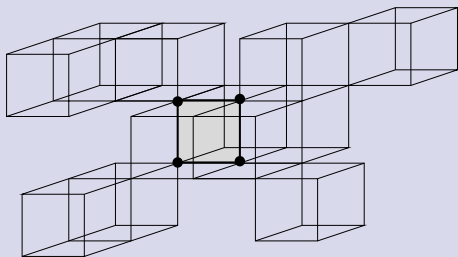
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Theorem

In any dimension, the critical kernel of X is a retraction of X .



$X_2 = \text{Critic}(X_1)$, a retraction of X_1 such that $\text{Critic}(X_2) = X_2$



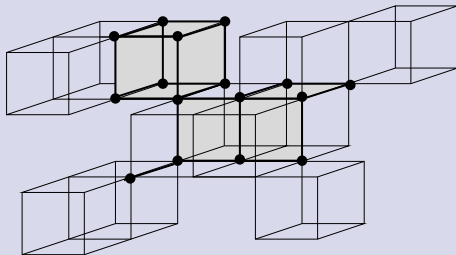
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Main theorem (2)

Theorem

In any dimension, the critical kernel of X is a retraction of X .

Furthermore, if Y is any principal subcomplex of X such that Y contains the critical kernel of X , then Y is a retraction of X .



$Critic(X)$



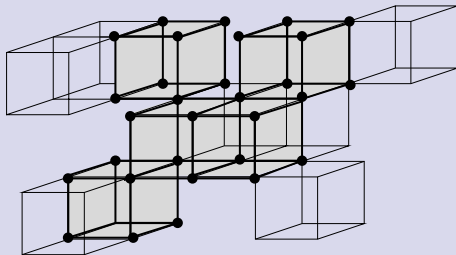
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Main theorem (2)

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A complex Y which contains $Critic(X)$



Main theorem (2)

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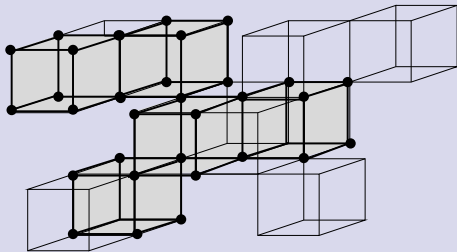
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Theorem

In any dimension, the critical kernel of X is a retraction of X .

Furthermore, if Y is any principal subcomplex of X such that Y contains the critical kernel of X , then Y is a retraction of X .



Another complex Z which contains $Critic(X)$



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Part III

New 3D Parallel Thinning Scheme



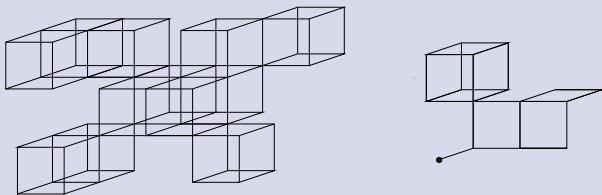
Crucial kernels: motivation

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The critical kernel of a set of voxels is not always a set of voxels



In the following, we assume that X is a set of voxels (*i.e.*, a complex in which each principal face is a 3-face).

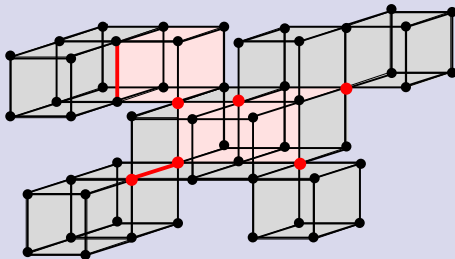


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Maximal critical face

Definition

- A face f in X is a **maximal critical face**, or an **M-critical face**, if f is a critical face which is not strictly included in any other critical face.



Critical faces

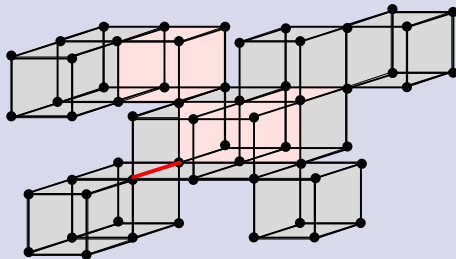


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M-critical faces



Crucial kernel

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Let K be a given subset of X . Loosely speaking,

- the **crucial kernel of X constrained by K** is a particular, uniquely defined set of voxels which contains all the M -critical faces of X and which contains K .



Corollary of the main theorem

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The following property is an easy consequence of the main theorem:

Property

Let K be a set composed of 3-faces of X . The crucial kernel of X constrained by K is a retraction of X .



Generic thinning scheme

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The crucial kernel of X constrained by K is denoted by $Cruc(X, K)$.

Definition

Let $K \subseteq X$.

- Let $\langle X_0, X_1, \dots, X_k \rangle$ be the unique sequence such that
 - $X_0 = X$, and
 - $X_k = Cruc(X_k, K)$, and
 - $X_i = Cruc(X_{i-1}, K)$, $i = 1, \dots, k$.
- The set X_k is the K -skeleton of X constrained by K .

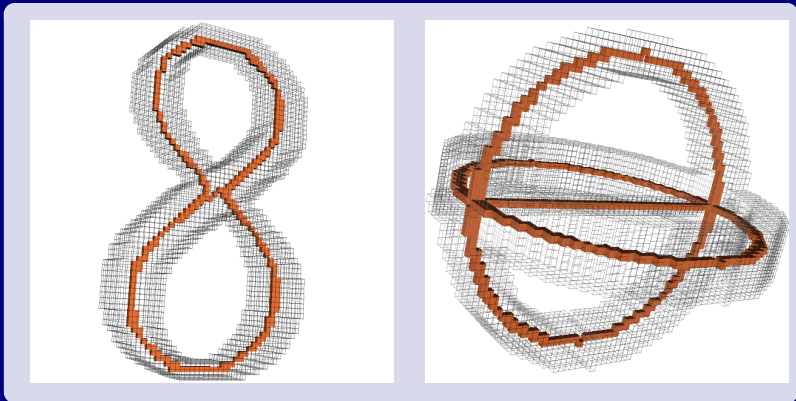


Illustration: with $K = \emptyset$

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Illustration: with $K \subseteq AM(X)$

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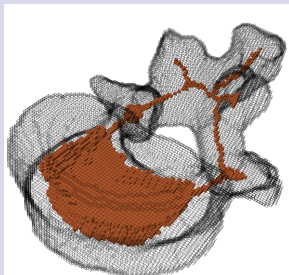
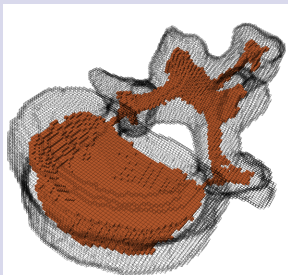
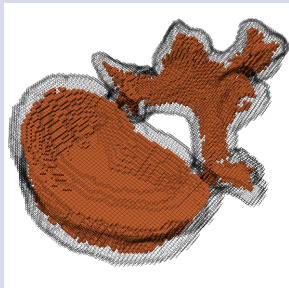
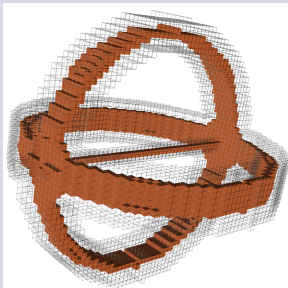


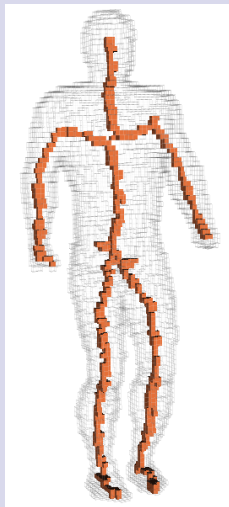
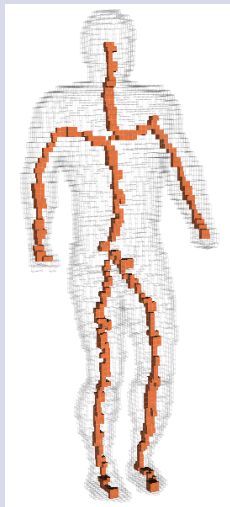
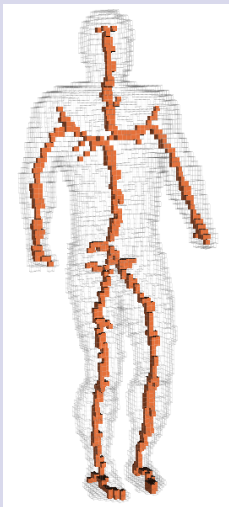


Illustration: curvilinear skeletons

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Part IV

Local characterizations and thinning algorithm

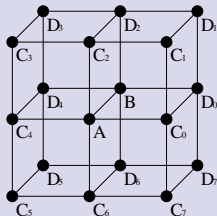


Local conditions (3D)

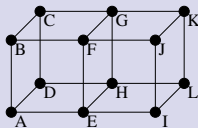
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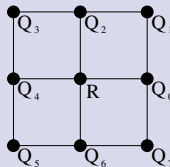
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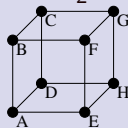
M_2



M_1



M'_2



M_0

Masks for 2-crucial (M_2), 1-crucial (M_1), and 0-crucial (M_0) voxels (3-faces), M'_2 is a configuration derived from M_2 . Here, a voxel is represented by a point.



Thinning algorithm

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Algorithm SK^3 (Input: X , $K \subseteq X$; Output: X)

01. Repeat Until Stability
02. $R_3 :=$ set of voxels which are critical for X or which are in K
03. $R_2 :=$ set of voxels which are 2-crucial and included in $X \setminus R_3$
04. $R_1 :=$ set of voxels which are 1-crucial and included in $X \setminus (R_3 \cup R_2)$
05. $R_0 :=$ set of voxels which are 0-crucial and included in $X \setminus (R_3 \cup R_2 \cup R_1)$
06. $X := R_3 \cup R_2 \cup R_1 \cup R_0$



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Part V

Epilogue



Conclusion

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The salient outcomes of this work are:

- the definition and local characterization of 3D crucial faces, allowing for *fast and simple implementations*,
- a *new generic parallel 3D thinning scheme*,
- a parallel algorithm for a *minimal symmetric constrained skeleton*

As far as we know, all previously proposed symmetric thinning conditions are not sufficiently "powerful" for removing enough points in order to obtain a skeleton such as the minimal skeleton presented in this talk.



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Perspectives

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- general skeletons (*i.e.*, which are not necessarily principal subcomplexes)
 - link with P -simple points
 - link with minimal non-simple sets
 - N -dimensional thinning



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Questions

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