
Recognizing hierarchical watersheds

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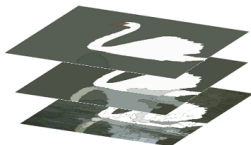
Hierarchical watersheds

- Sequences of nested partitions such that each partition is a watershed of a filtering of the initial relief/map according to regional attributes, e.g., on geometric, photometric, or learned, information
- Good performance on natural images [P18]
- Hierarchies of segmentation can be equivalently represented by saliency maps

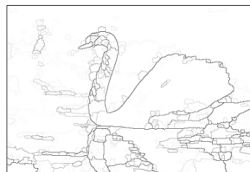
Original image



Hierarchical watershed \mathcal{H}



Saliency map of \mathcal{H}



[P18] B. Perret, J Cousty, S. Guimaraes, D. Maia. *Evaluation of hierarchical watersheds*. *IEEE TIP*. 2018.

Combination of hierarchies (of watersheds)

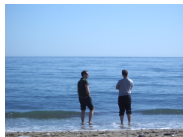
- Based on saliency maps combination [C17, M17]
 - with, e.g., infimum, supremum, or linear combination

[C17] J. Cousty, L. Najman, Y. Kenmochi, S. Guimarães. *Hierarchical segmentations with graphs: quasi-flat zones, minimum spanning trees, and saliency maps*. JMIV. 2017

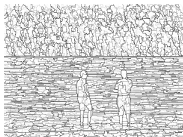
[M17] D. S. Maia, A. de A. Araujo, J. Cousty, L. Najman, B. Perret, H. Talbot. *Evaluation of combinations of watershed hierarchies*. ISMM. 2017

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Original



Area attribute



Dynamics attribute



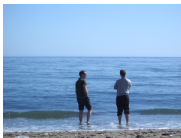
One level of each hierarchy with 75 regions

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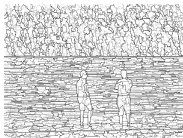
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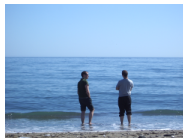
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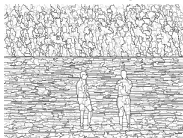
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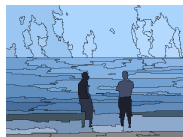
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Combination



One level of each hierarchy with 75 regions

Does the combinations of hierarchical watersheds always result in a hierarchical watershed?

Hierarchical segmentation

Hierarchical segmentation technique proposed in [A11]:

[A11] P. Arbelaez, M. Maire, C. Fowlkes and J. Malik. *Contour detection and hierarchical image segmentation. IEEE transactions on pattern analysis and machine intelligence. 2011*

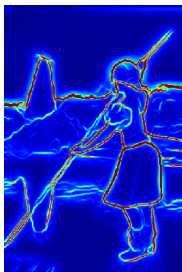
Hierarchical segmentation

Hierarchical segmentation technique proposed in [A11]:

- Contour-detection with multiscale cue combination (*mPb*)



I



mPb

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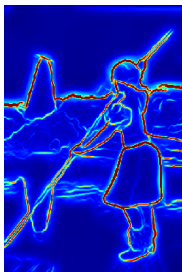
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\mathcal{H}

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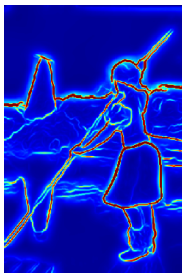
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mPb



\mathcal{H}

Is \mathcal{H} a hierarchical watershed of mPb ?

Recognition of hierarchical watersheds

Problem

Given a hierarchy \mathcal{H} and a weighted graph (G, w) :

- Recognize if \mathcal{H} is a hierarchical watershed of (G, w)
- **Naive approach:** factorial time complexity

Recognition of hierarchical watersheds

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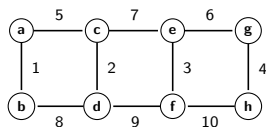
Contributions

- Characterization of hierarchical watersheds
- Quasi-linear algorithm to recognize the hierarchical watersheds

- 1 Hierarchical watersheds
- 2 Characterization of hierarchical watersheds
- 3 Algorithm to recognize hierarchical watersheds
- 4 Conclusion and perspectives

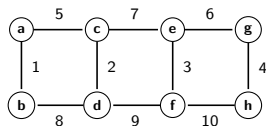
Graph settings

- (G, w) is an edge-weighted graph
 - which can be a pixel-adjacency graph
 - edge weight can represent a gradient of intensity



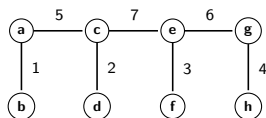
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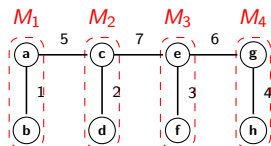
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Graph settings

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- For simplification, we consider that *the edges of G has pairwise distinct weights for w , which implies that (G, w) has a single MST*
- $\mathcal{M} = (M_0, \dots, M_\ell)$ is any sequence of the regional minima of w ranked by importance according to some given attribute

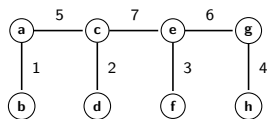


Hierarchical watersheds

- A *hierarchical watershed* of (G, w) for \mathcal{M} is a hierarchy of partitions $(\mathbf{P}_0, \dots, \mathbf{P}_\ell)$ such that, for any $i \in \{0, \dots, \ell\}$:
 - \mathbf{P}_i is the connected component partition of a minimum spanning forest rooted in the minima ranked after i

Hierarchical watersheds

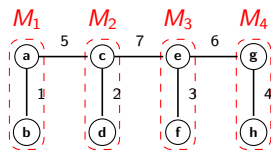
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(G, w)

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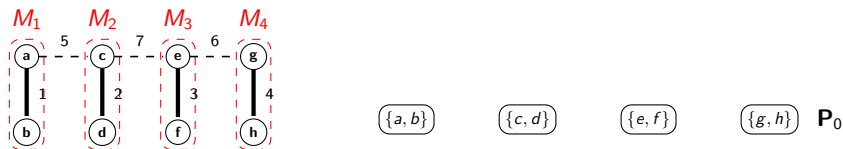


Minima of w

$$\mathcal{M} = (M_1, M_2, M_3, M_4)$$

Hierarchical watersheds

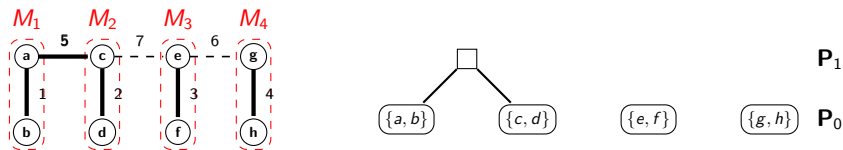
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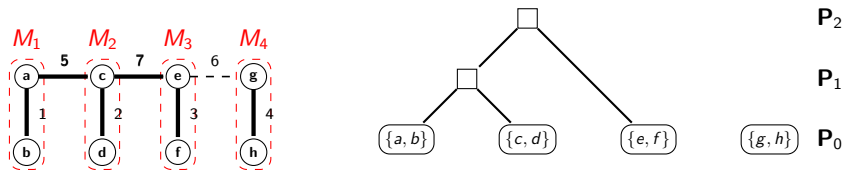
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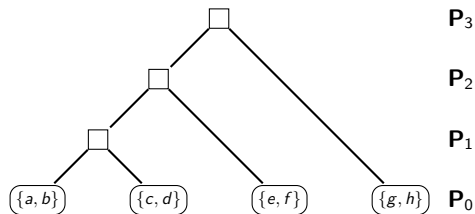
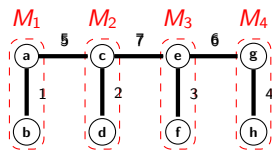
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$(\mathbf{P}_0, \mathbf{P}_1, \mathbf{P}_2, \mathbf{P}_3)$:
hierarchical watershed of (G, w) by $\mathcal{M} = (M_1, M_2, M_3, M_4)$

Hierarchical watersheds

Definition

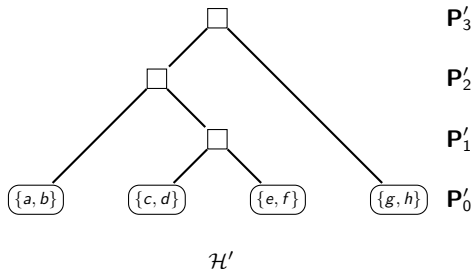
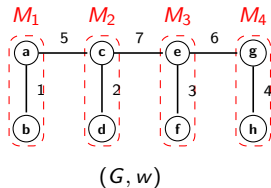
We say that \mathcal{H} is a *hierarchical watershed of* (G, w) if there is a sequence \mathcal{M} of minima such that \mathcal{H} is the hierarchical watershed of (G, w) for \mathcal{M}

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Remark: there are hierarchies which are not hierarchical watersheds of (G, w) , e.g., $(\mathbf{P}'_0, \mathbf{P}'_1, \mathbf{P}'_2, \mathbf{P}'_3)$ is **not** a hierarchical watershed of (G, w)



Outlines

- 1 Hierarchical watersheds
- 2 Characterization of hierarchical watersheds**
- 3 Algorithm to recognize hierarchical watersheds
- 4 Conclusion and perspectives

Characterization of hierarchical watersheds

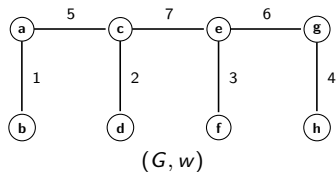
Key notions to present the characterization of hierarchical watersheds (Theorem 3):

- Binary partition hierarchy by altitude ordering (single linkage clustering with connectivity constraint) [C13]
- One-side increasing map

[C13] J. Cousty, L. Najman, B. Perret. *Constructive links between some morphological hierarchies on edge-weighted graphs*. ISMM 2013.

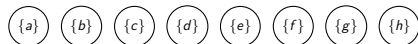
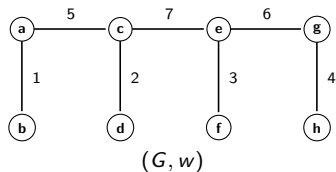
Binary partition hierarchy

- ⇒
- 1. binary partition hierarchy
 - 2. one-side increasing map
 - 3. Theorem 3



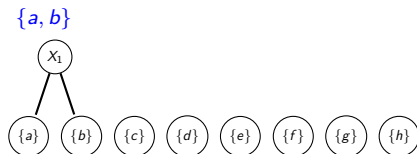
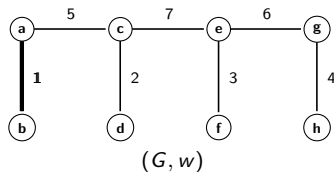
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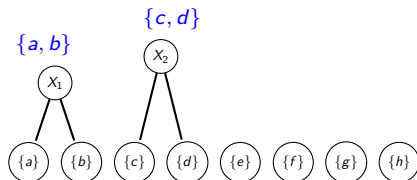
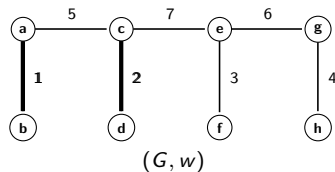
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Any non-leaf region R of \mathcal{B} can be mapped to an edge u_R of G which is then called the building edge of R (shown in blue)

Binary partition hierarchy

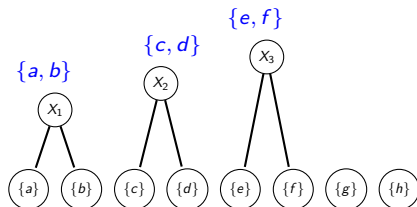
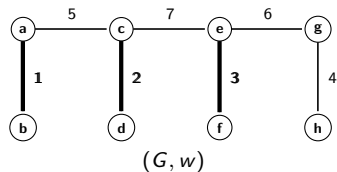
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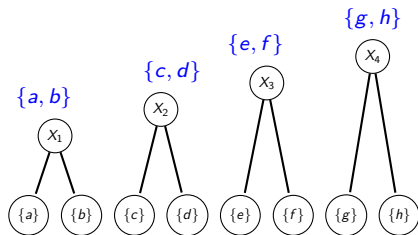
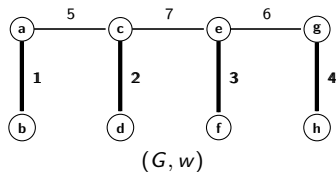
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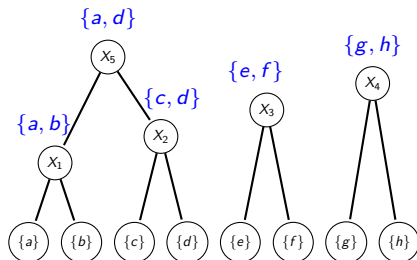
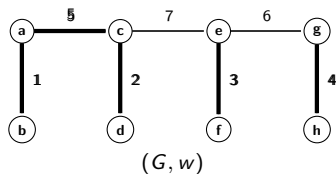
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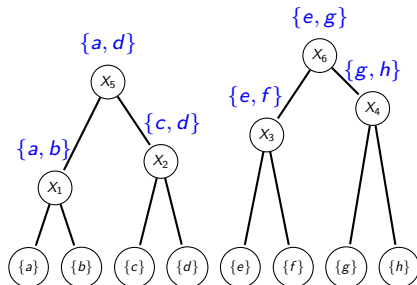
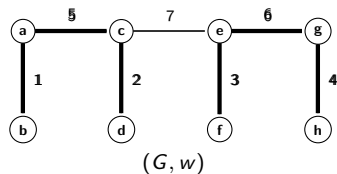
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Binary partition hierarchy

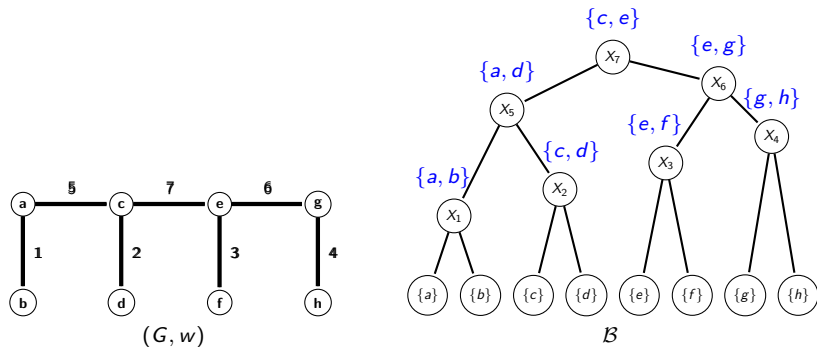
- ⇒ Characterization of HW:
1. binary partition hierarchy
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 3. Theorem 3



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Binary partition hierarchy

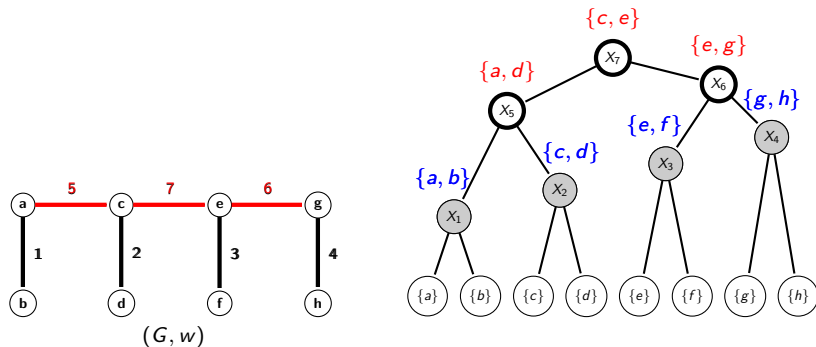
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Minima (in grey) and watershed-cut edges (in red)

One-side increasing map (intuitive idea)

Characterization of HW:
⇒ 1. binary partition hierarchy
2. one-side increasing map
3. Theorem 3

In order for a hierarchy \mathcal{H} to be a hierarchical watershed of a weighted graph (G, w) , we need:

- The finest level of \mathcal{H} to be the watershed segmentation of (G, w) ;
- Exactly one pair of regions to be merged at each level of the hierarchy; and
- Any region to be first merged to their “most similar” neighbors before being merged to their “least similar” neighbors.

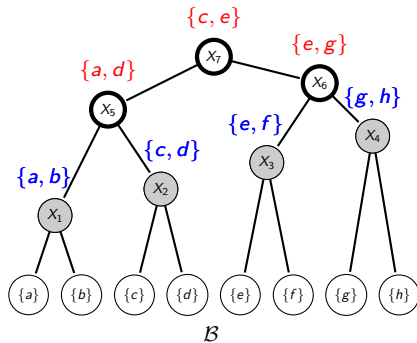
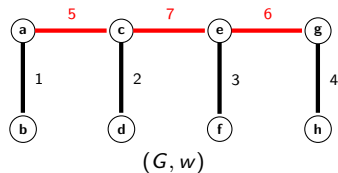
Definition (one-side increasing map)

Given a weighted graph (G, w) , let \mathcal{B} be the binary partition hierarchy of w . We say that a map f from E into \mathbb{R}^+ is a *one-side increasing map* for \mathcal{B} if:

- 1 $range(f) = \{0, \dots, n - 1\}$;
- 2 for any u in E , $f(u) > 0$ if and only if u is a watershed-cut edge of w ; and
- 3 for any u in E , there exists a child R of R_u such that $f(u) \geq \vee\{f(v)$ such that R_v is included in $R\}$, where $\vee\{\} = 0$.

One-side increasing map

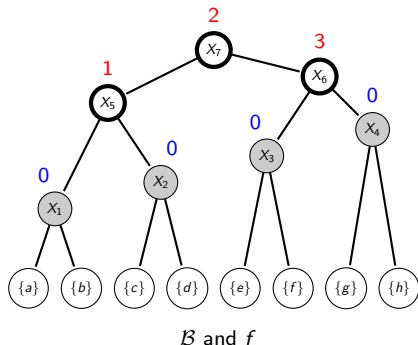
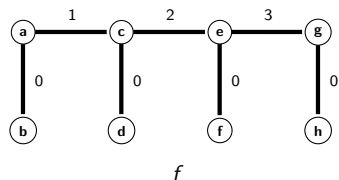
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Minima (in grey) and watershed-cut edges (in red)

One-side increasing map (example)

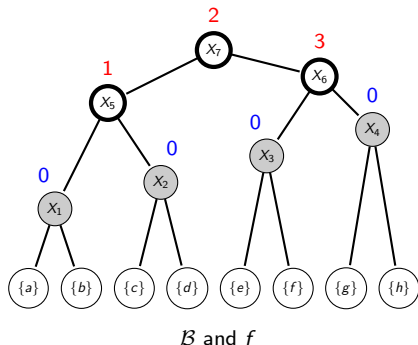
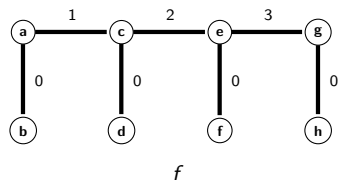
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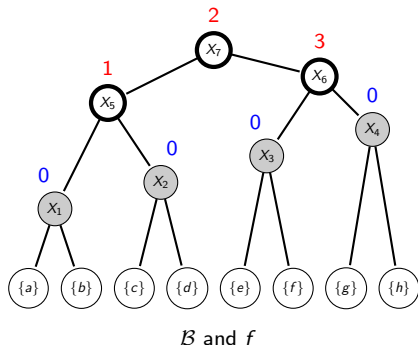
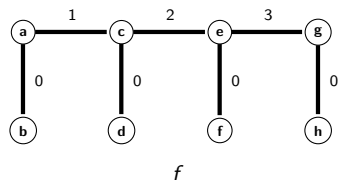
- Characterization of HW:
⇒ 1. binary partition hierarchy
2. one-side increasing map
3. Theorem 3



$$\text{range}(f) = \{0, \dots, 3\}?$$

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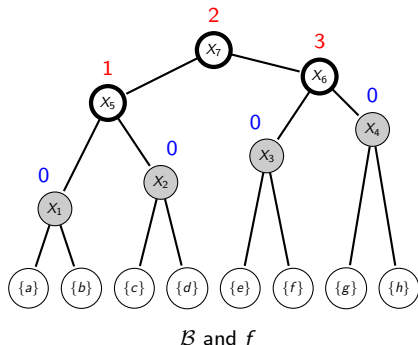
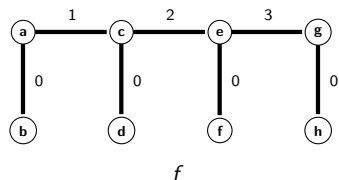
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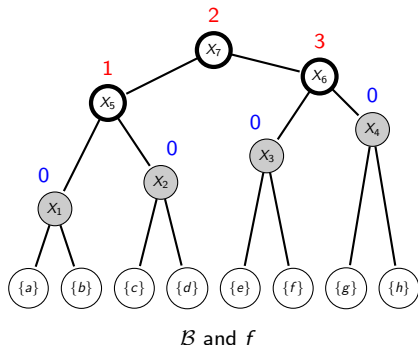
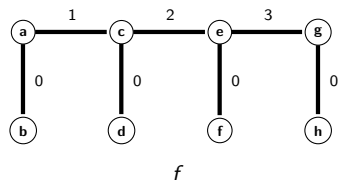
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$f(u) > 0$ if and only if u is a watershed-cut edge of w ?

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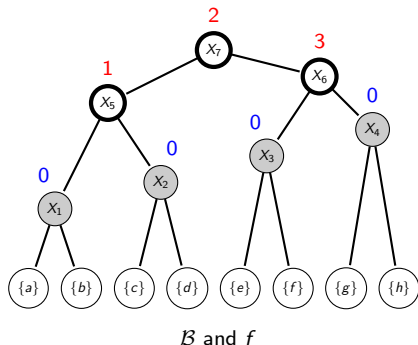
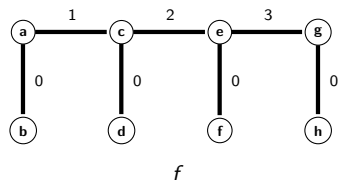
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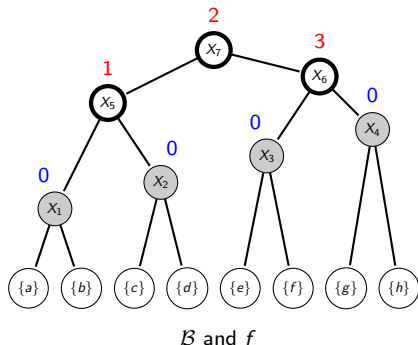
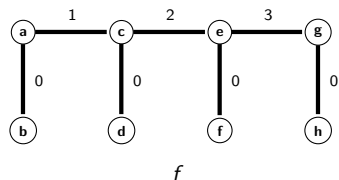
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for any u in E , there exists a child R of R_u such that $f(u) \geq \vee\{f(v)$
such that R_v is included in $R\}$?

One-side increasing map (example)

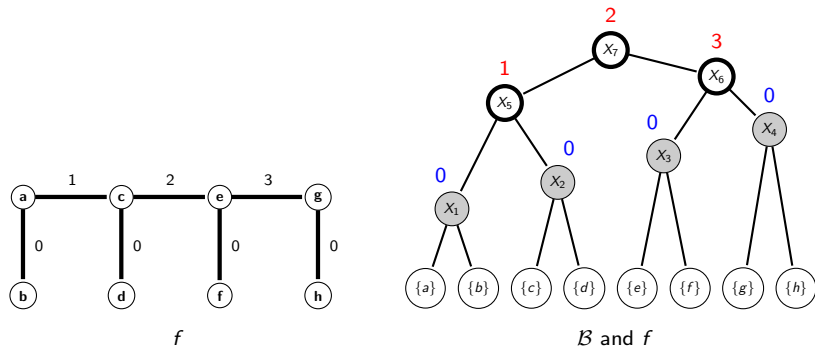
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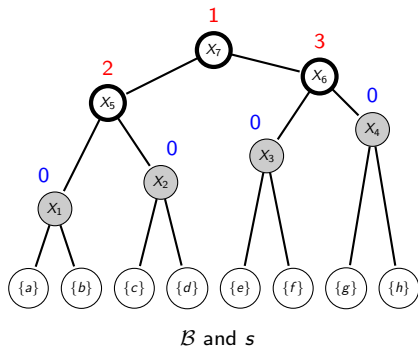
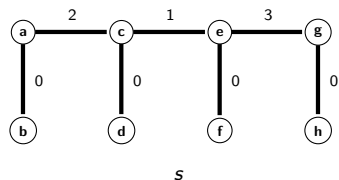
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Therefore, f is a one-side increasing map for \mathcal{B}

One-side increasing map (counter-example)

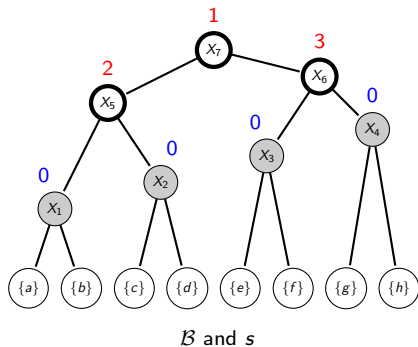
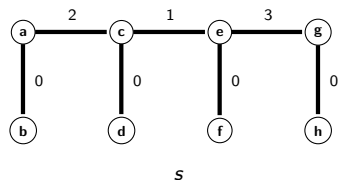
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Minima (in grey) and watershed-cut edges (in red)

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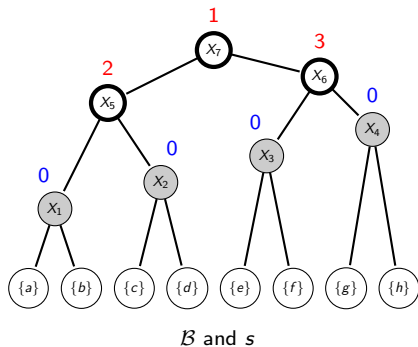
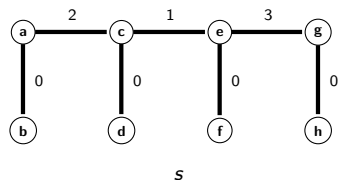
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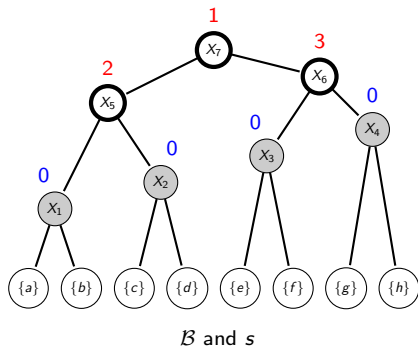
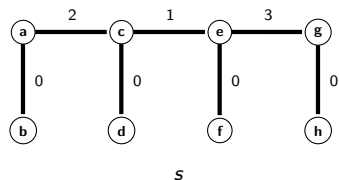
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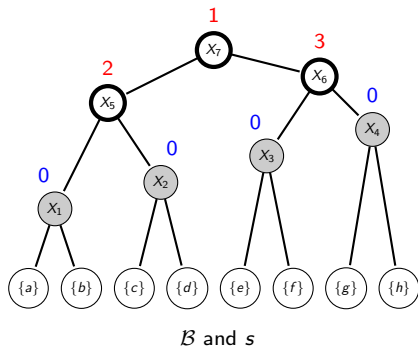
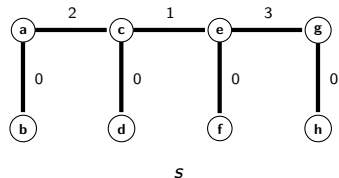
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$s(u) > 0$ if and only if u is a watershed-cut edge of w ?

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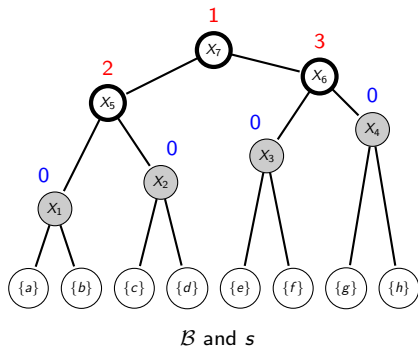
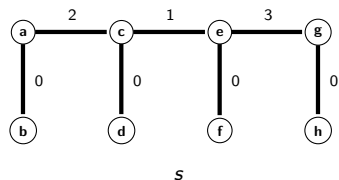
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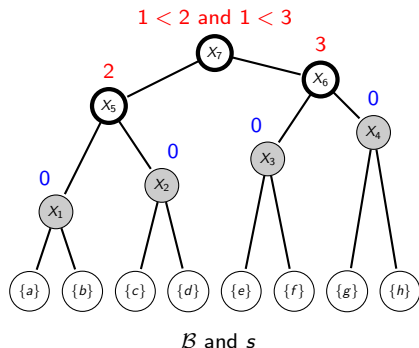
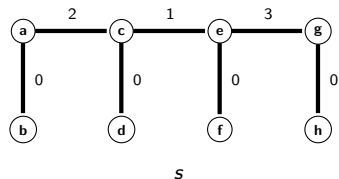
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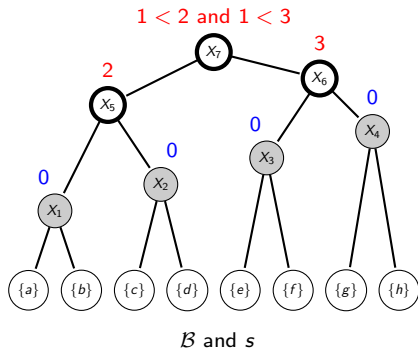
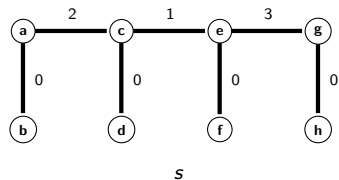
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One-side increasing map (counter-example)

- Characterization of HW:
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 3. Theorem 3
- ⇒



Therefore, s is *not* a one-side increasing map for \mathcal{B}

Characterization of hierarchical watersheds

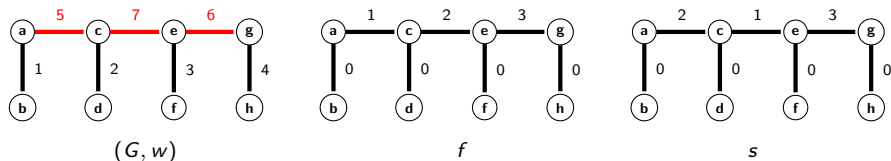
Theorem (characterization of hierarchical watersheds)

- *Let (G, w) be a weighted graph and let \mathcal{B} be the binary partition hierarchy of w . Let \mathcal{H} be a hierarchy and let $\Phi(\mathcal{H})$ be the saliency map of \mathcal{H} .*
- *The hierarchy \mathcal{H} is a hierarchical watershed of (G, w) if and only if $\Phi(\mathcal{H})$ is a one-side increasing map for \mathcal{B} .*

Characterization of hierarchical watersheds

Theorem (characterization of hierarchical watersheds)

- Let (G, w) be a weighted graph and let \mathcal{B} be the binary partition hierarchy of w . Let \mathcal{H} be a hierarchy and let $\Phi(\mathcal{H})$ be the saliency map of \mathcal{H} .
- The hierarchy \mathcal{H} is a hierarchical watershed of (G, w) if and only if $\Phi(\mathcal{H})$ is a one-side increasing map for \mathcal{B} .



Then, f **is** the saliency of a hierarchical watershed of (G, w) , but s **is not**.

Outlines

- 1 Hierarchical watersheds
- 2 Characterization of hierarchical watersheds
- 3 Algorithm to recognize hierarchical watersheds**
- 4 Conclusion and perspectives

Algorithm to recognize hierarchical watersheds

We determine if a map f is the saliency map of a hierarchical watershed of (G, w) through the following steps:

- 1 Compute the binary partition hierarchy \mathcal{B} of w
- 2 Compute the set $WS(w)$ of watershed-cut edges of w
- 3 Compute the number n of minima of w
- 4 For each edge u of G , compute the value $Max[u]$ which corresponds to $\vee\{f(v) \mid R_u \subseteq R_v\}$
- 5 For each edge u of G :
 - 1 If $f(u)$ not in $\{0, \dots, n-1\}$, then return **false**
 - 2 If u is not in $WS(w)$ and $f(u) \neq 0$, then return **false**
 - 3 If u is in $WS(w)$ and if $f(u)$ is not unique, then return **false**
 - 4 If u is in $WS(w)$ and if $Max[u] < Max[v_1]$ and $Max[u] < Max[v_2]$, then return **false**
- 6 return **true**

Algorithm to recognize hierarchical watersheds

Complexity analysis:

- As shown in [N13], the binary partition hierarchy \mathcal{B} of (G, w) can be computed in **quasi-linear time** with respect to the number of edges of G
- Then, given the hierarchy \mathcal{B} , the minima and the watershed-cut edges of (G, w) can be obtained in **linear time**
- The array Max can be also obtained in **linear time** if computed from the leaves to the root of \mathcal{B}
- Finally, the three conditions for f to be a one-side increasing map of \mathcal{B} can be verified in **linear time** as well
- *Therefore, the proposed algorithm has a **quasi-linear time complexity***

[N13] L. Najman, J. Cousty, B. Perret. *Playing with Kruskal: algorithms for morphological trees in edge-weighted graphs.. ISMM 2013.*

Outlines

- 1 Hierarchical watersheds
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Conclusion and perspectives

Summary

- *Characterization of hierarchical watersheds through binary partition hierarchies*
- *Quasi-linear time algorithm to recognize hierarchical watersheds*

Perspectives

- *Answer the question: does the combination of hierarchical watersheds always result in a hierarchical watershed?*
- *Extension to arbitrary weighted graphs*
- *Waterhseding operator that converts any hierarchy into a hierarchical watershed (ISMM2019)*